

	<b><i>Command</i></b>	<b><i>Command Description</i></b>
1	ST1FOR	Stepper 1 forward
2	ST1BAK	Stepper 1 backward
3	ST2FOR	Stepper 2 forward
4	ST2BAK	Stepper 2 backward
5	STBFOR	Both Stepper Forward – simultaneously
6	STBBAK	Both Stepper Backward – simultaneously
7	STSYNC	Get steppers both in same position in case of slip
8	AMSTOP	Emergency stop. Stop All motors. E.g. Over Current
9	ST1FXX	Move Stepper 1 XX (999 steps max) positions forward
10	ST1BXX	Move Stepper 1 XX (999 steps max) positions backward
11	ST2FXX	Move Stepper 2 XX (999 steps max) positions forward
12	ST2BXX	Move Stepper 2 XX (999 steps max) positions backward
13	DC2FOR	DC Motor 2 ON/forward
14	DC2BAK	DC Motor 2 ON/backward
15	DC2OFF	DC Motor 2 OFF
16	DC1FOR	DC Motor 1 ON/forward
17	DC1BAK	DC Motor 1 ON/backward
18	DC1OFF	DC Motor 1 OFF
19	DCBFOR	DC Both Motor forward
20	DCBBAK	DC Both Motor backward
21	DCBOFF	DC Both Motor OFF
22	SV2FOR	Servo 1 forward
23	SV2BAK	Servo 1 backward
24	SV2MID	Servo 1 Middle position
25	SV2HLD	Servo 1 Hold
26	SV1FOR	Servo 2 forward
27	SV1BAK	Servo 2 backward
28	SV1MID	Servo 2 Middle position
29	SV1HLD	Servo 2 hold
30	MTYPEX	Transmit Motor type back
31	STDELX	Configure stepper motor delay
32	ECHOST	Configure Echo Default ON
33	AMONXX	All Motors ON
34	MONOFF	Do not monitor current consumption
35	CMONON	Monitor current consumption
36	RESUME	Enable Motors after overcurrent condition